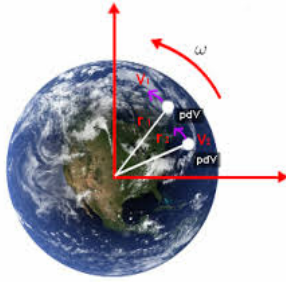


## 9.5 Rotational Work and Rotational Energy



## Rotational Work

Analogous to linear work, but force is replaced by torque; distance replaced by angular displacement:

$W = FS$	W = work (J) F = linear force (N) s = arc length (m)
$W = F(r_{\perp} \cdot \theta)$	$r_{\perp}$ = radius (m) $\theta$ = angle (rad)
$W = \tau \cdot \theta$	$\tau$ = torque (m•N)
$W = I \cdot \alpha \cdot \theta$	I = moment of inertia (kg•m <sup>2</sup> ) $\alpha$ = angular acceleration (rad/s <sup>2</sup> )

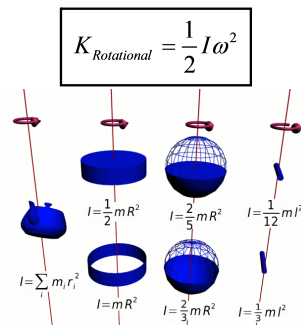
## Rotational Power

Is derived directly from rotational work, in that it is an amount of energy discharged in an amount of time:

AP Equation	$P = \frac{\Delta E}{\Delta t} = \tau \left( \frac{\theta}{t} \right) = \tau \omega$	P = Power (J/s)
		E = Energy (J)
		t = time (s)
		$\tau$ = torque (m•N)
		$\theta$ = angle (rad)
		$\omega$ = angular speed (rad/s)

## Rotational Kinetic Energy

For any rotating body:



## Rotational Work-Energy Theorem

We learned that kinetic energy equals an amount of work done:

$$W_{\text{net}} = K - K_0 = \Delta K$$

In rotational motion, this can be derived thusly:

$$W_{\text{net}} = I \alpha \theta$$

$$\omega^2 = \omega_0^2 + 2\alpha\theta$$

$$\alpha\theta = \frac{\omega^2 - \omega_0^2}{2}$$

$$W_{\text{net}} = I \left( \frac{\omega^2 - \omega_0^2}{2} \right) = \frac{1}{2} I \omega^2 - \frac{1}{2} I \omega_0^2 = \Delta K$$

## Rotating, Translating Bodies

What if you've got a rotating, AND translating body, like a rolling wheel (no slipping)?

Look at rotational and translational dynamics, using center of mass (CM):

Rotational:  $K_{\text{rotational}} = \frac{1}{2} I_{\text{CM}} \omega^2$

Translational:  $K_{\text{translational}} = \frac{1}{2} m v_{\text{CM}}^2$

Combined:  $K_{\text{total}} = \frac{1}{2} I_{\text{CM}} \omega^2 + \frac{1}{2} m v_{\text{CM}}^2$

### Rotational Energy Problem 1

The CM of a solid 1.0 kg cylinder ( $I = 1/2 mr^2$ ) rolls without slipping at a speed of 1.8 m/s.

What is the cylinder's rotational kinetic energy?

Note 1: radius cancels out.

Note 2: review equation:

$$\omega = \frac{v_{CM}}{r}$$

$$K_{rotational} = \frac{1}{2} I \omega^2 = \frac{1}{2} \left( \frac{1}{2} mr^2 \right) \left( \frac{v_{CM}}{r} \right)^2$$

$$= \frac{1}{4} mv_{CM}^2 = \frac{1}{4} (1.0 \text{ kg})(1.8 \text{ m/s})^2 = 0.81 \text{ J}$$

### Rotational Energy Problem 2

A uniform, solid 1.0 kg cylinder ( $I = 1/2 mr^2$ ) rolls without slipping at a speed of 1.8 m/s.

What is the cylinder's translational kinetic energy?

$$K_{translational} = \frac{1}{2} mv_{CM}^2 = \frac{1}{2} (1.0 \text{ kg})(1.8 \text{ m/s})^2 = 1.6 \text{ J}$$

$$K_{total} = \frac{1}{2} I_{CM} \omega^2 + \frac{1}{2} mv_{CM}^2$$

$$= 0.81 \text{ J} + 1.62 \text{ J} = 2.4 \text{ J}$$

### Rotational Energy Problem 3

A uniform, solid 1.0 kg cylinder ( $I = 1/2 mr^2$ ) rolls without slipping at a speed of 1.8 m/s.

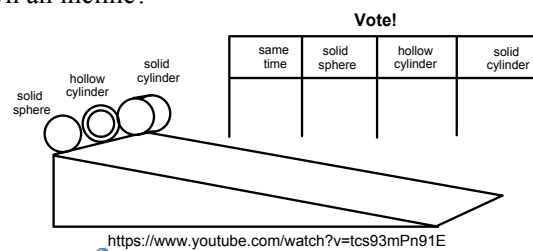
What percentage of the total is rotational kinetic energy?

$$\frac{K_{Rotational}}{K_{Total}} = \frac{0.81 \text{ J}}{2.4 \text{ J}} = 33.8\%$$

Thus, most of the energy is in translational form.

### Inertial Race Physics Democracy!

Consider a sphere, a solid cylinder, and a hollow cylinder (like an empty can) of the same masses and radii. Which will reach the bottom first, if you roll them down an incline?



### Inertial Race Answer

The sphere wins every time, its moment of inertia is the lowest, so its angular acceleration is largest:

$$\alpha = \frac{\tau}{I}$$

Sphere:  $I = \frac{2mr^2}{5}$

Solid Cylinder:  $I = \frac{1}{2} mr^2$

Hollow Cylinder:  $I = mr^2$

### Homework 9.5

Read 8.5 in your book  
Problems 9.5 in your Booklet  
Due: Next Class